

Formula Sheet for PHYS152

$$\Delta x = x_f - x_i$$

$$v_{avg} = \frac{\Delta x}{\Delta t} = \frac{x_f - x_i}{t_f - t_i}$$

$$v = \lim_{t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

$$S_{avg} = \frac{Total Distance}{\Delta t}$$

$$a_{avg} = \frac{\Delta v}{\Delta t} = \frac{v_f - v_i}{t_f - t_i}$$

$$a = \lim_{t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt} = \frac{d^2 x}{dt^2}$$

$$v = v_0 + a t$$

$$x = x_0 + v_0 t + \frac{1}{2} a t^2$$

$$v^2 - v_0^2 = 2 a (x - x_0)$$

$$x = \int v dt$$

$$v = \int a dt$$

$$A_x = A \cos \theta,$$

$$A_y = A \sin \theta.$$

$$\text{If } \vec{a} = \vec{b} + \vec{c}, \text{ then}$$

$$a_x = b_x + c_x,$$

$$a_y = b_y + c_y,$$

$$a_z = b_z + c_z.$$

$$v_x = v_{x0} = v_0 \cos \theta_0 = \text{const.}$$

$$x - x_0 = v_0 \cos \theta_0 t$$

$$v_{y0} = v_0 \sin \theta_0$$

$$v_y = v_{y0} - g t$$

$$y = y_0 + v_{y0} t - \frac{1}{2} g t^2$$

$$v_y^2 = v_{y0}^2 - 2 g (y - y_0)$$

$$t_T = \frac{2 v_0 \sin \theta_0}{g}$$

$$R = \frac{v_0^2 \sin 2\theta_0}{g}$$

$$\vec{F}_{net} = m \vec{a}$$

$$\vec{F}_{12} = -\vec{F}_{21}$$

$$w = mg$$

$$f_{s,max} = \mu_s N$$

$$f_k = \mu_k N$$

$$\mu_s > \mu_k$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

$$a = \frac{v^2}{r}$$

$$T = \frac{2\pi r}{v}$$

$$F = m \frac{v^2}{r}$$

$$W = F d \cos \theta$$

$$K = \frac{1}{2} m v^2$$

$$W_{net} = K_f - K_i = \Delta K$$

$$U = PE$$

$$U_g = mgy$$

$$U_{elastic} = \frac{1}{2} k x^2$$

$$E_{mech} = K + U$$

$$K_f + U_f = K_i + U_i$$

$$-f_k d = \Delta K + \Delta U$$

$$\Delta U = U_f - U_i$$

$$F = -kx$$

$$W = \frac{1}{2} k x^2$$

$$P = \frac{W}{\Delta t}$$

$$P = F \cdot \vec{v}$$

$$\vec{p}=m\vec{v}$$

$$\sum \vec{F}_{ext} = \frac{\Delta \vec{p}_{tot}}{\Delta t}$$

$$\vec{I} = \vec{F}_{avg} \cdot \Delta t = \Delta \vec{p}$$

$$m_1\vec{v}_1+m_2\vec{v}_2=m_1\vec{v}_1'+m_2\vec{v}_2'$$

$$\frac{1}{2}m_1v_1^2+\frac{1}{2}m_2v_2^2=\frac{1}{2}m_1v_1'^2+\frac{1}{2}m_2v_2'^2$$

$$v_1-v_2=-(v_1'-v_2')$$

$$x_{CM}=\frac{1}{M}\sum_i m_ix_i$$

$$y_{CM}=\frac{1}{M}\sum_i m_iy_i$$

$$z_{CM}=\frac{1}{M}\sum_i m_iz_i$$

$$M=\sum_i m_i$$

$$\tau=rF\sin\theta$$

$$\tau=r_{\perp}F=rF_{\perp}$$

$$\sum \tau = I\alpha$$

$$\omega=\omega_0+\alpha t$$

$$\theta=\theta_0+\omega_0t+\frac{1}{2}\alpha t^2$$

$$\omega^2-\omega_0^2=2\alpha(\theta-\theta_0)$$

$$s=r\theta$$

$$v=r\omega$$

$$a_t=r\alpha$$

$$I=\sum_i m_ir_i^2$$

$$KE_R=\frac{1}{2}I\omega^2$$

$$L=I\omega$$

$$I_1\omega_1=I_2\omega_2$$

$$\vec{F}_{net}=0$$

$$\sum_i F_{i,x}=0$$

$$\sum_i F_{i,y}=0$$

$$\vec{\tau}_{net}=0$$

$$\sum_i \tau_{i,x}=0$$