

Butcher Tableaux

The general form of a Runge-Kutta scheme (state $n \rightarrow n + 1$) to solve the ODE

$$\frac{dy}{dx} = f(x, y)$$

is

$$\begin{aligned} \delta y_0 &= \delta x f(x_n + a_0 \delta x, y_n) \\ \delta y_1 &= \delta x f(x_n + a_1 \delta x, y_n + b_{10} \delta y_0) \\ \delta y_2 &= \delta x f(x_n + a_2 \delta x, y_n + b_{20} \delta y_0 + b_{21} \delta y_1) \\ &\vdots \\ \delta y_{s-1} &= \delta x f\left(x_n + a_{s-1} \delta x, y_n + \sum_{i=0}^{s-2} b_{s-1,i} \delta y_i\right) \\ y_{n+1} &= y_n + \sum_{i=0}^{s-1} c_i \delta y_i \end{aligned}$$

(see Numerical Recipes, Sec. 17.2). This is not quite the syntax used previously in class or in the book—the count starts at 0 to facilitate translation of the algorithm into Python. The method is defined by s , the number of stages, the offsets a_i and b_{ji} , and the weights c_i .

The whole scheme is often written compactly in the form of a *Butcher tableau*:

a_0	b_{00}	b_{01}	\cdots	$b_{0,s-1}$
a_1	b_{10}	b_{11}	\cdots	$b_{1,s-1}$
\vdots	\vdots	\vdots	\ddots	\vdots
a_{s-1}	$b_{s-1,0}$	$b_{s-1,1}$	\cdots	$b_{s-1,s-1}$
	c_0	c_1	\cdots	c_{s-1}

Butcher tableaux for some of the schemes we have explored follow.

Euler

0	
	1

Implicit Euler

1	1
	1

Midpoint

0	
$\frac{1}{2}$	$\frac{1}{2}$
	0 1

3/8 Rule

0				
$\frac{1}{3}$	$\frac{1}{3}$			
$\frac{2}{3}$	$-\frac{1}{3}$	1		
1	1	-1	1	
	$\frac{1}{8}$	$\frac{3}{8}$	$\frac{3}{8}$	$\frac{1}{8}$

Runge-Kutta 4

0				
$\frac{1}{2}$	$\frac{1}{2}$			
$\frac{1}{2}$	0	$\frac{1}{2}$		
1	0	0	1	
	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{6}$

Note that blank spaces in the 2-D b array should be interpreted as zeros, and any nonzero element on or above the diagonal means that this stage in the algorithm is implicit.