

Lectures 14-15:
**Beam Theory: Architecture for Cells
and Skeletons**

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Beam Theory:

- macromolecules can be viewed as networks of one-dimensional elements (chains of amino acids, chains of base pairs, ...)
- beam theory addresses the mechanics of these networks
- a bead treated as a rod with elastic properties

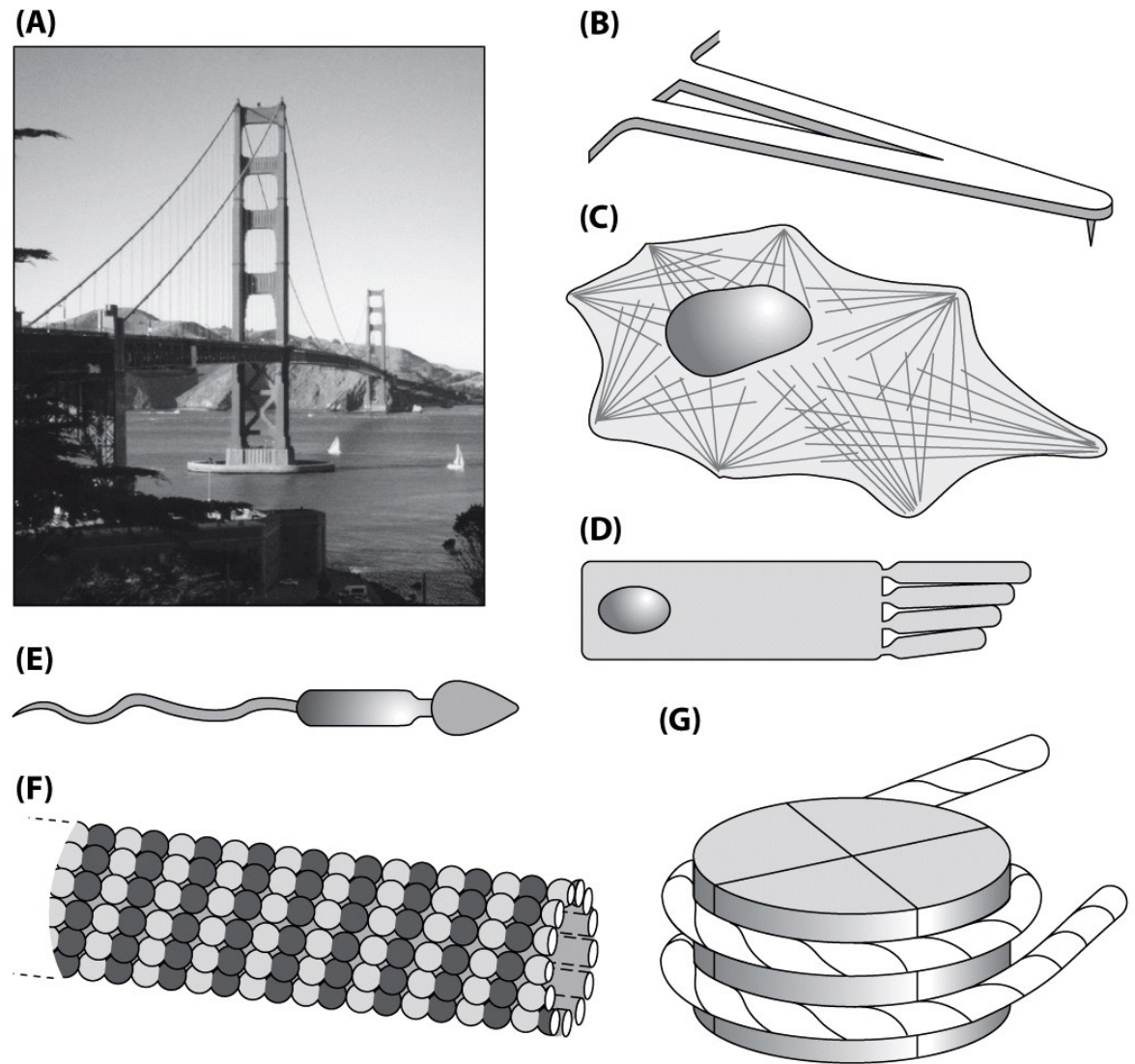


Figure 10.1 Physical Biology of the Cell (© Garland Science 2009)

Three types of deformations

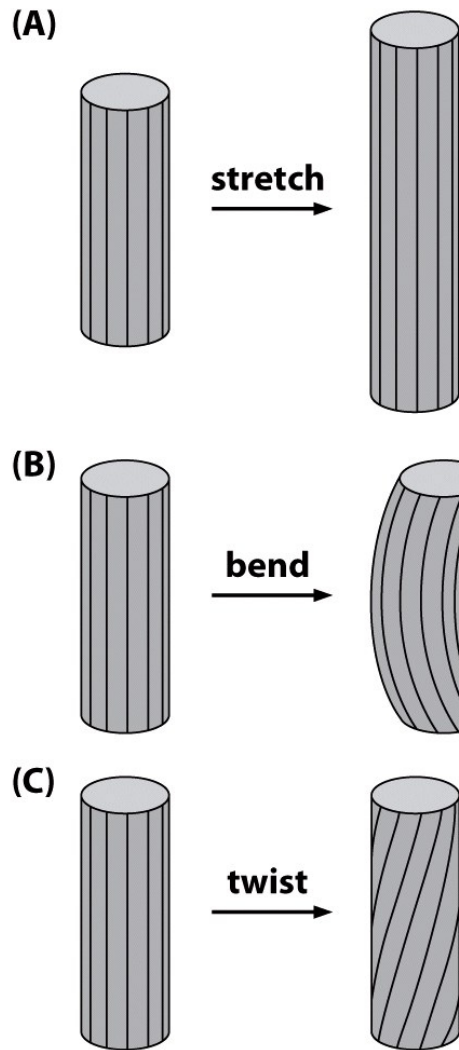


Figure 10.2 Physical Biology of the Cell (© Garland Science 2009)

Bending of a beam: a neutral plane

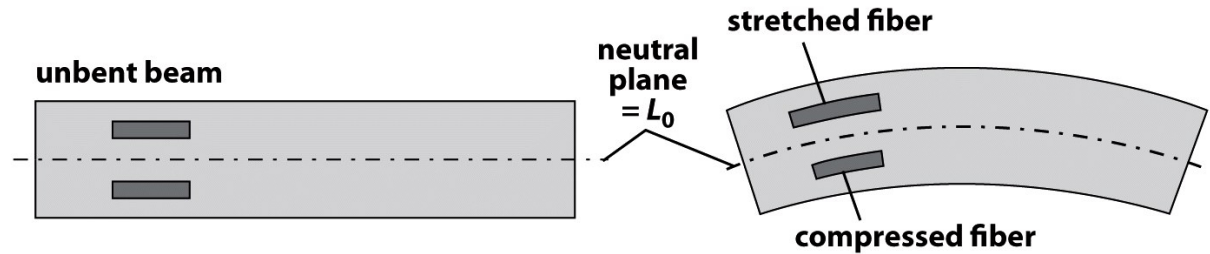


Figure 10.3 Physical Biology of the Cell (© Garland Science 2009)

Microscopic interpretation of bending

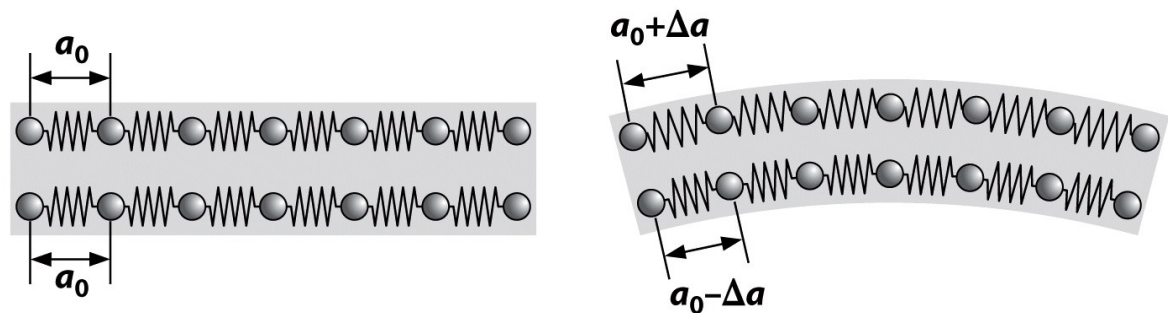


Figure 10.5 Physical Biology of the Cell (© Garland Science 2009)

Imagine a beam split up in segments each with own curvature

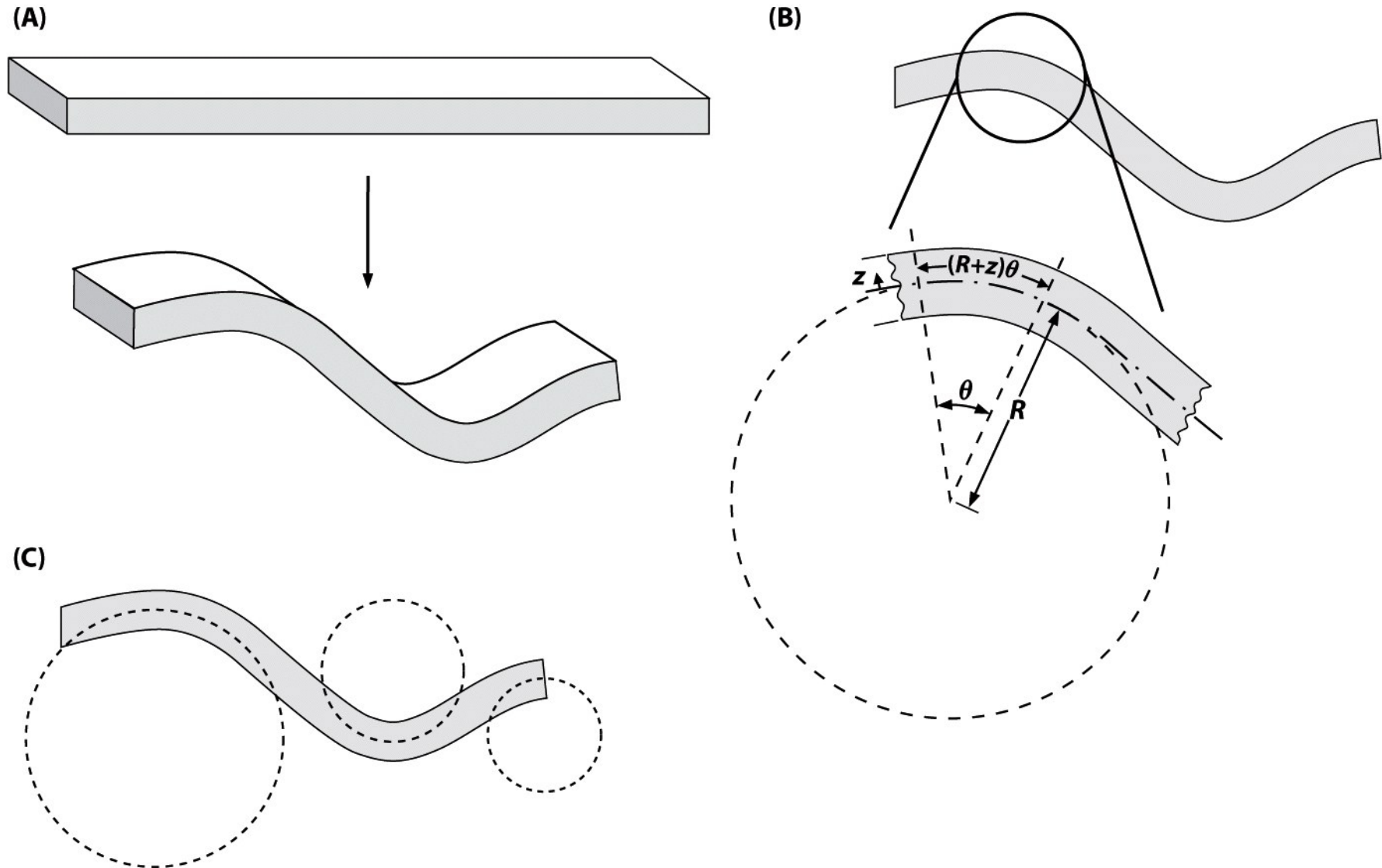


Figure 10.4 Physical Biology of the Cell (© Garland Science 2009)

Note that the extent of extension or compression is a linear function of the distance from the neutral plane z :

$$\theta = \frac{L_0}{R} \quad L(z) = (R+z)\theta = \frac{(R+z)L_0}{R}$$

$$\Delta L(z) = L(z) - L_0 = (R+z)\frac{L_0}{R} - L_0 = z\frac{L_0}{R}$$

Extensional strain $\varepsilon(z)$ at a distance z is defined as:

$$\varepsilon(z) = \frac{\Delta L(z)}{L_0} = \frac{z}{R}$$

such that material above the neutral axis is stretched, $\varepsilon(z) > 0$, and material below the neutral axis is compressed, $\varepsilon(z) < 0$.

The energy cost is a quadratic function of the strain (Hooke's law):

$$W(\varepsilon) = \frac{1}{2} E \varepsilon^2 = \frac{1}{2} E \left(\frac{\Delta L}{L_0} \right)^2 \quad E \dots \text{the Young modulus}$$

A more precise calculation of the total strain energy of the beam:

$$E_{\text{bend}} = L_0 \int_{\partial\Omega} dA \frac{E}{2R^2} z^2 = \frac{EIL}{2R^2}$$

$$I = \int_{\partial\Omega} z^2 dA \quad I \dots \text{geometric moment}$$

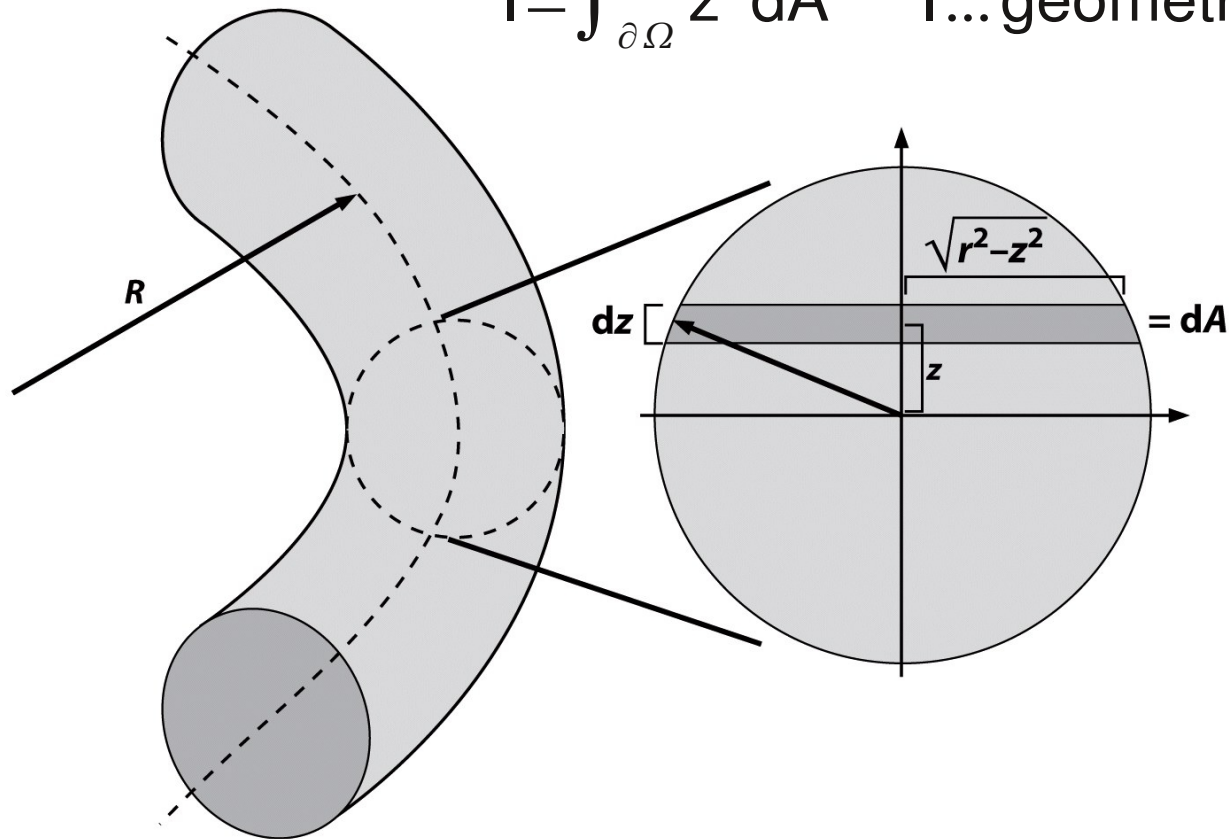


Figure 10.6 Physical Biology of the Cell (© Garland Science 2009)

$$E_{\text{bend}} = \frac{EIL}{2R^2} \quad \text{For } L = 2\pi R, \text{ we get: } E_{\text{loop}} = \frac{\pi EI}{R}$$

We can introduce flexural rigidity: $K_{\text{eff}} = EI$

Then the energy of bending is: $E_{\text{bend}} = \frac{K_{\text{eff}}}{2} \int_0^L ds \frac{1}{R(s)^2}$

In general, we can express the bending energy in terms of a curvature:

$$\kappa = \frac{1}{R(s)}$$

And we finally get:

$$E_{\text{bend}} = \frac{K_{\text{eff}}}{2} \int_0^L \left| \frac{dt}{ds} \right|^2 ds \quad \left| \frac{dt}{ds} \right| \dots \text{derivative of the tangent vector}$$

Persistence Length and Stiffness

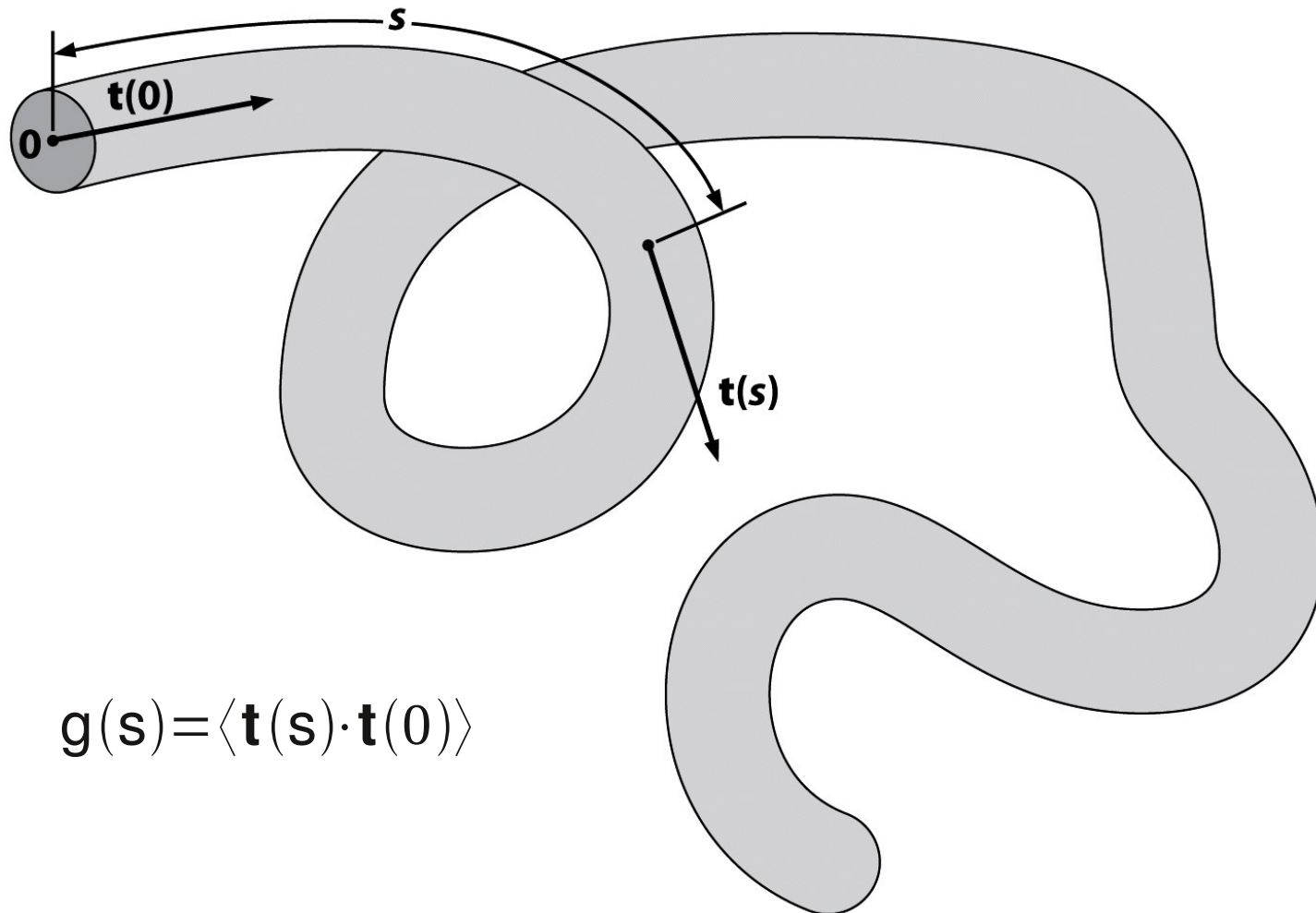
- *persistence length* is a measure of the competition between the entropy (“randomizer”) and energy cost of bending
- equate the deterministic energy cost to thermal energy:

$$k_B T \approx \frac{EI}{2R^2}$$

- persistence length is the length of a polymer for which the radius of curvature is equal to the length of polymer itself: $\xi_P \approx R \approx L$
- estimate of the persistence length:

$$\xi_P \approx \frac{EI}{2k_B T}$$

Persistence length characterizes the correlations in the tangent vectors at different positions along the polymer



$$g(s) = \langle \mathbf{t}(s) \cdot \mathbf{t}(0) \rangle$$

Figure 10.7 Physical Biology of the Cell (© Garland Science 2009)

General properties of the tangent-tangent correlation function:

$$g(s=0)=1 \quad g(s \rightarrow \infty)=0$$
$$g(s)=\langle \mathbf{t}(s) \cdot \mathbf{t}(0) \rangle = e^{-s/\xi_p}$$

Relationship between flexural rigidity and persistence length:

→ short beam of length: $L \approx s \ll \xi_p$

→ short beam is only slightly bent: $E_{\text{bend}} = \frac{EIL}{2R^2} \approx \frac{EI}{2s} \theta^2 \quad (s = R\theta)$

→ if a tangent at $s=0$ points in the z -direction, then:

$$g(s) = \langle \cos \theta(s) \rangle \quad \theta \ll 1 \Rightarrow \cos \theta \approx 1 - \frac{1}{2} \theta^2$$

$$g(s) \approx 1 - \frac{1}{2} \langle \theta^2 \rangle$$

Calculate: $\langle \theta(\mathbf{s})^2 \rangle = \frac{1}{Z} \int_0^{2\pi} d\Phi \int_0^\pi d\theta \sin \theta \theta^2 e^{-(EI/2k_B T s)\theta^2}$

$$Z = \int_0^{2\pi} d\Phi \int_0^\pi d\theta \sin \theta e^{-(EI/2k_B T s)\theta^2}$$

We apply the same trick as before:

$$\langle \theta(\mathbf{s})^2 \rangle = -\frac{1}{Z} \frac{2k_B T s}{EI} \frac{\partial Z}{\partial E}$$

Thus, the only integral we really need to calculate is:

$$Z = \int_0^{2\pi} d\Phi \int_0^\pi d\theta \sin \theta e^{-(EI/2k_B T s)\theta^2} \approx \int_0^{2\pi} d\Phi \int_0^\pi d\theta \theta e^{-(EI/2k_B T s)\theta^2}$$

where we used the Taylor expansion for $\sin \theta \approx \theta$

$$Z = \frac{2\pi k_B T s}{EI} \int_0^\infty du e^{-u} = \frac{2\pi k_B T s}{EI} \quad \frac{1}{Z} \frac{\partial Z}{\partial E} = -\frac{1}{E}$$

$$\langle \theta(\mathbf{s})^2 \rangle = \frac{2k_B T s}{EI} \quad \langle g(\mathbf{s}) \rangle \approx 1 - \frac{k_B T}{EI} s = 1 - \frac{s}{\xi_P} \quad \xi_P = \frac{EI}{k_B T} = \frac{K_{\text{eff}}}{k_B T}$$

The Worm-Like Chain Model

→ contains both the entropic and elastic bending contributions to the free energy

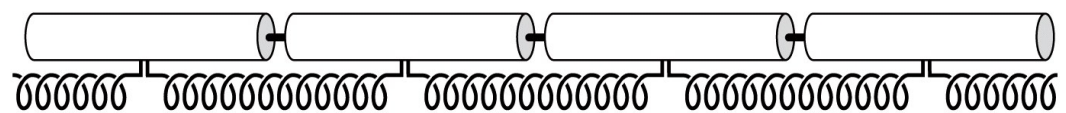
→ concept: chains are cylinders connected by flexible links

(A)

- no bending (optimal E)

- non-optimal S

(A)



(B)

- bending (non-optimal E)

- more optimal S

(B)

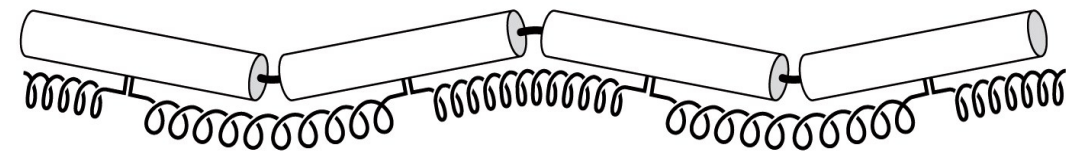


Figure 10.8 Physical Biology of the Cell (© Garland Science 2009)

$$Z = \int D\mathbf{t}(s) \exp\left(-\frac{\xi_P}{2} \int_0^L \left|\frac{d\mathbf{t}}{ds}\right|^2 ds\right)$$

Sum over all possible $\mathbf{t}(s)$
curves of length L :
Feynman Path Integral

To calculate the force-extension curve, we need to include the work done by the external force F (along the z -direction), which adds:

$$-F \int_0^L t_z ds$$

such that an average change extension can be calculated as:

$$\langle z \rangle = \frac{1}{Z(f)} \int D\mathbf{t}(s) z \exp \left(\frac{-\xi_P}{2} \int_0^L \left| \frac{d\mathbf{t}(s)}{ds} \right|^2 ds + f \int_0^L t_z ds \right)$$

$Z(f)$... partition function in the presence of the force

$$F = k_B T f \text{ (} f \text{ has a unit of inverse length)}$$

Again, the same trick can be used to avoid a calculation of two path integrals:

$$\langle z \rangle = \frac{d \ln Z(f)}{df} \rightarrow \text{approx. solution: } f \xi_P = \frac{z}{L} + \frac{1}{4(1-z/L)^2} - \frac{1}{4}$$

(Appendix of Ch. 10)

Force-Extension Curve for a Worm-Like Chain Model

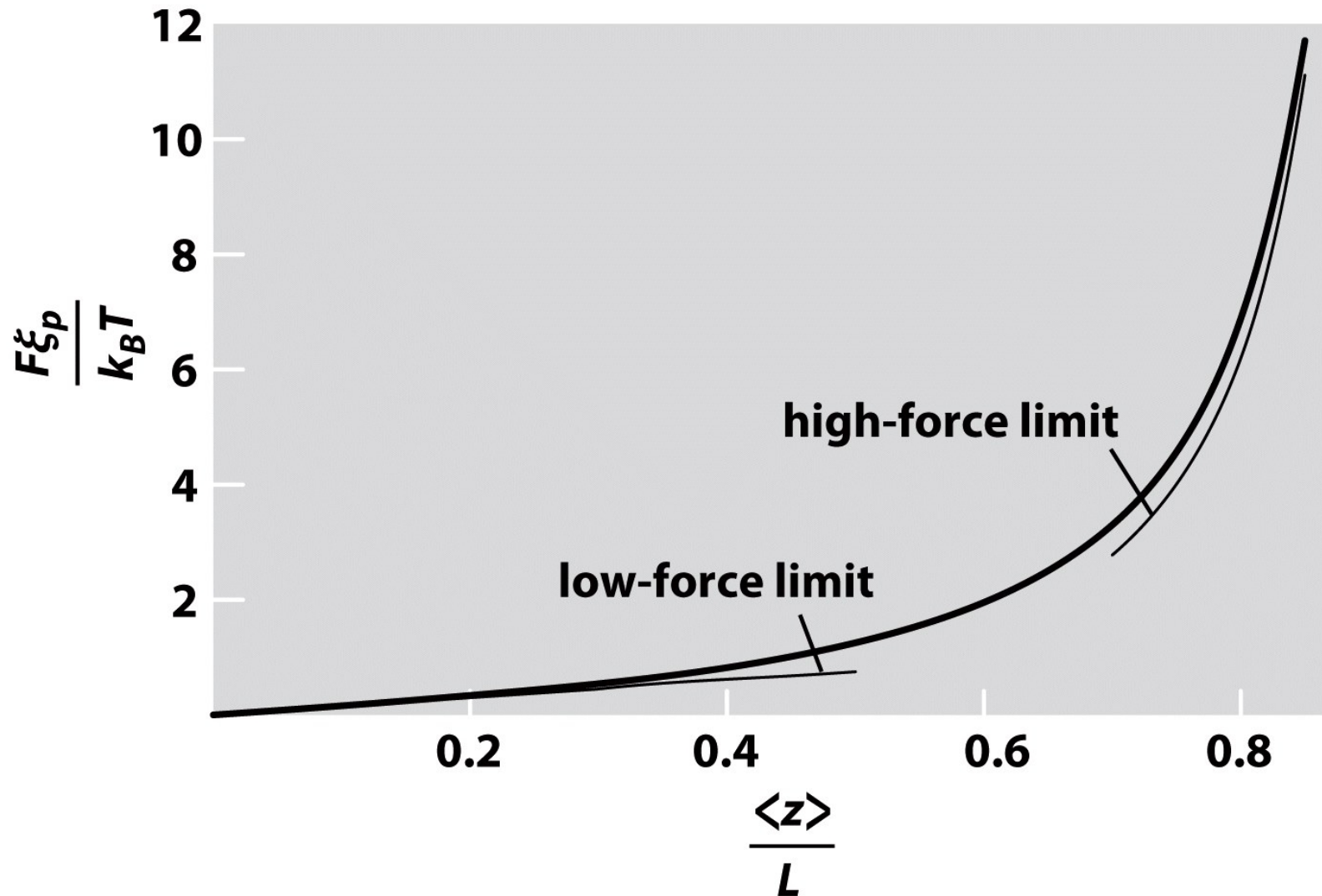


Figure 10.38 Physical Biology of the Cell (© Garland Science 2009)

The mechanics of transcriptional regulation

- ***lac* operon: genetic network that regulates the lactose metabolism in *E. coli***
- **consider lac repressor, a protein, which represses transcription by binding to DNA and initiating DNA loop formation**
- **Lac repressor: a tetrameric protein with three specific binding sites: O1, O2, and O3; loops can be either 401 or 92 bp long (401 x 0.34 nm = 136 nm; 92 x 0.34 nm = 31 nm < 50 nm)**
- **in eukaryotes, there are cis-regulatory regions that control developmental process by DNA loop formation**
- **bending of a DNA fragment that is smaller than the persistence length ξ_P !**

cis-regulatory region of DNA

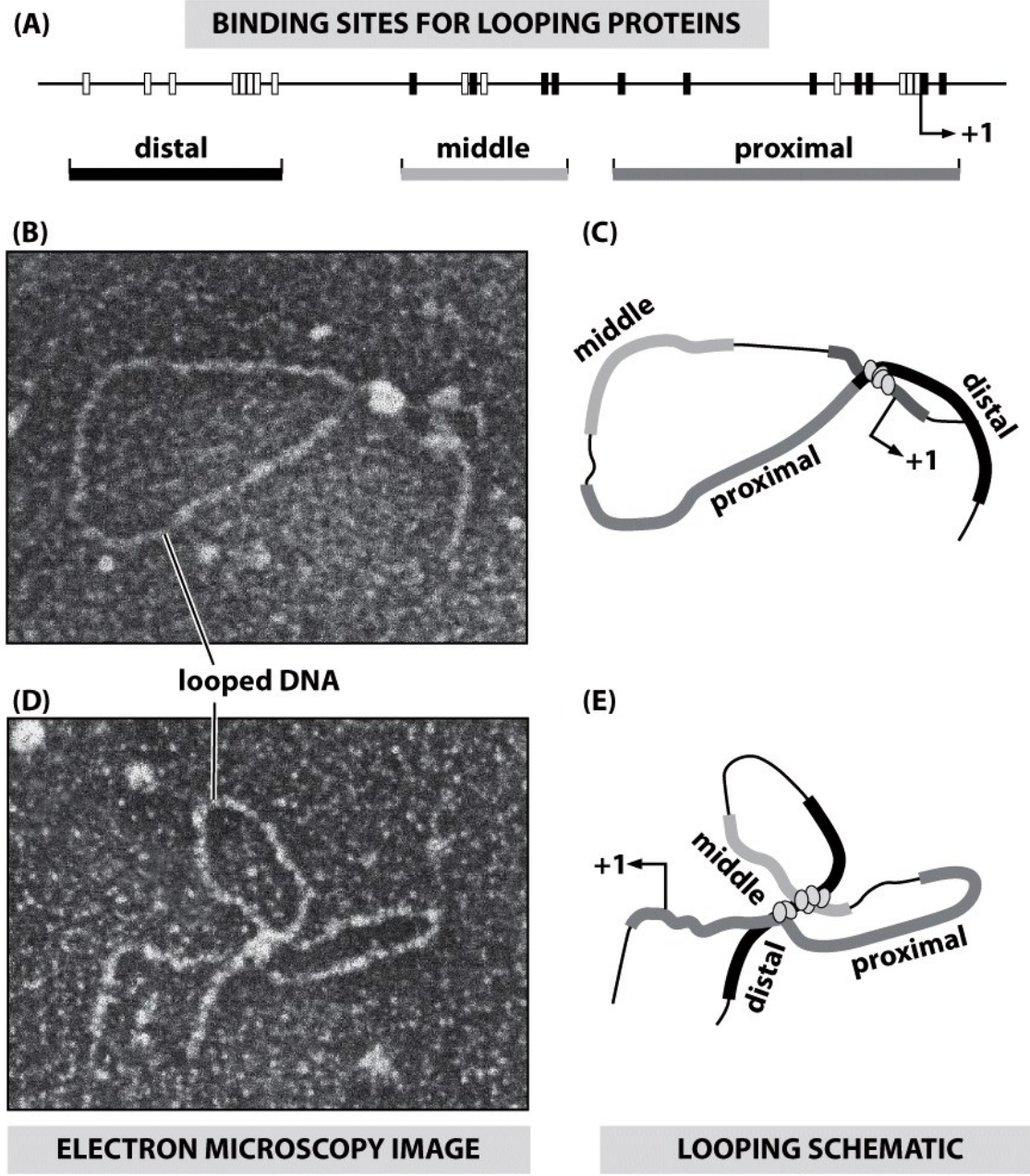


Figure 10.9 Physical Biology of the Cell (© Garland Science 2009)

Energetics of DNA looping

Bending energy of a loop with a radius R was calculated already:

$$E_{\text{loop}} = \frac{\xi_P \pi k_B T}{R}$$

For a DNA loop of length L, we take into account the following:

$$L = 2\pi R \quad \rightarrow \quad R = \frac{L}{2\pi} = \frac{\delta N_{\text{bp}}}{2\pi} \quad \text{where } \delta = 0.34 \text{ nm}$$

to obtain a more convenient bending energy of a DNA loop:

$$\frac{E_{\text{loop}}}{k_B T} = \frac{2\pi^2}{N_{\text{bp}}} \left(\frac{\xi_P}{\delta} \right) \approx \frac{3000}{N_{\text{bp}}}$$

expressed in terms of the number of base pairs. We used the estimate for the persistence length:

$$\xi_P = 50 \text{ nm}$$

The bending energy of DNA loops as a function of the number of base pairs in the DNA

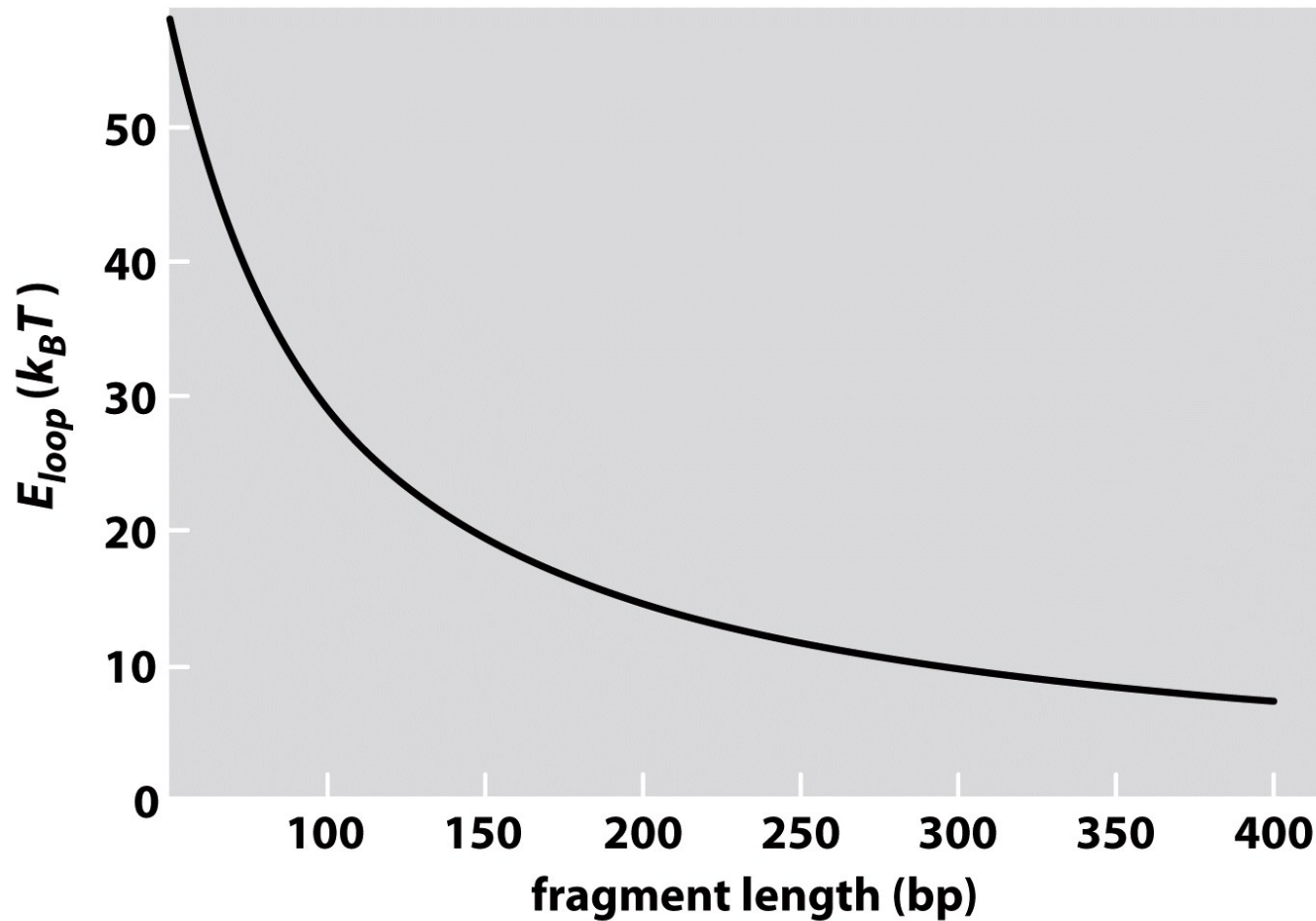


Figure 10.10 Physical Biology of the Cell (© Garland Science 2009)

Free Energy Estimate for DNA Looping: Elastic Energy Combined with Entropic Contribution

- long DNA fragments: entropic contribution unfavorable
- short DNA fragment: bending contribution unfavorable
- elastic and entropic contributions:

$$\Delta E_{\text{loop}} \approx \frac{3000 k_B T}{N_{\text{bp}}}$$

$$p_0 \propto \frac{1}{\sqrt{N_{\text{bp}}^3}} \rightarrow \Delta S_{\text{loop}} = k_B \ln p_0 = -k_B \left(\frac{3}{2} \ln N_{\text{bp}} + \text{const} \right)$$

- result in the total free energy change upon DNA looping:

$$\Delta G_{\text{loop}} = \Delta E_{\text{loop}} - T \Delta S_{\text{loop}} \approx k_B T \left(\frac{3000}{N_{\text{bp}}} + \frac{3}{2} \ln N_{\text{bp}} + \text{const} \right)$$

The looping free energy as a function of the number of base pairs as derived within a simple toy model

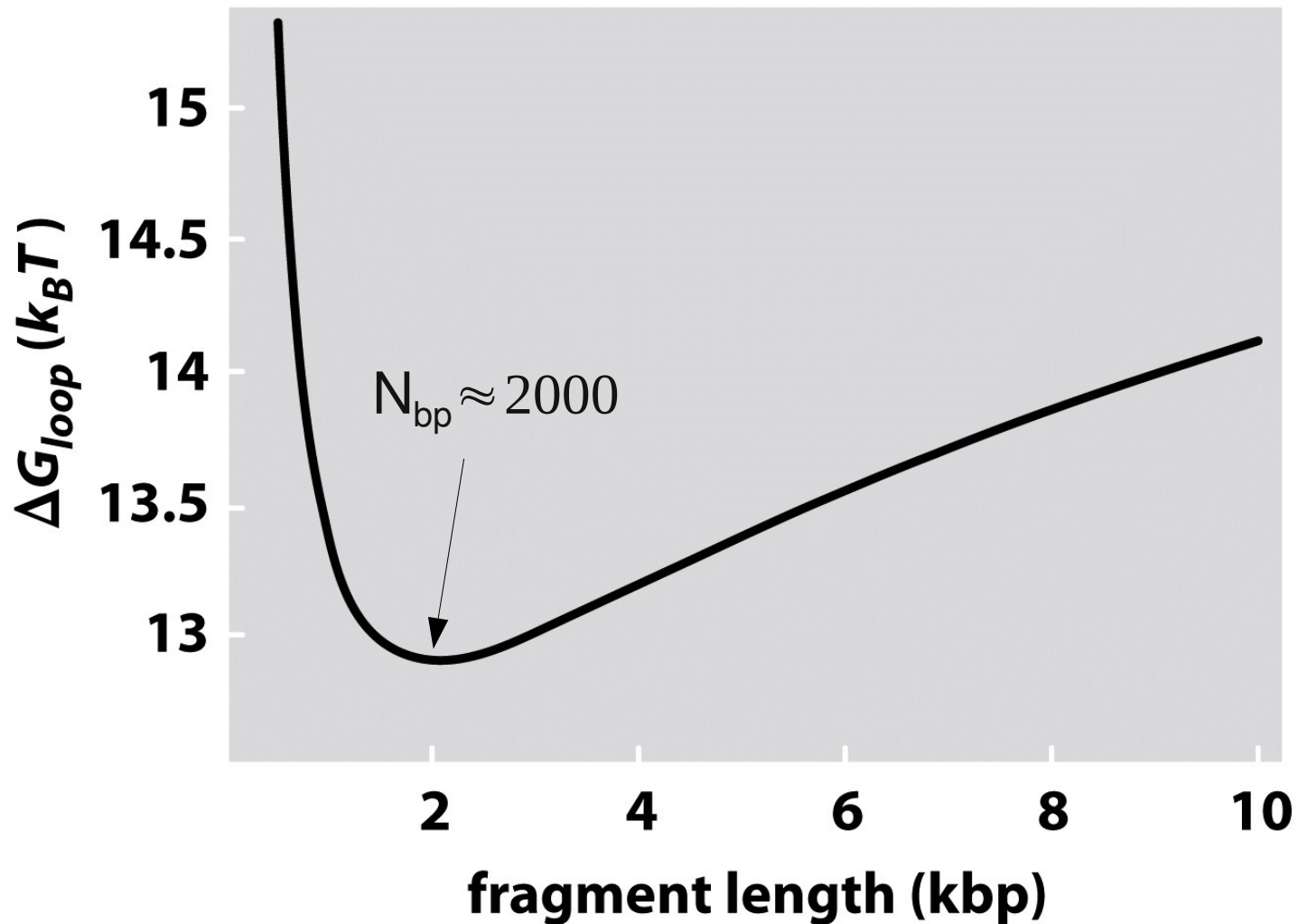


Figure 10.11 Physical Biology of the Cell (© Garland Science 2009)

Experimental data and the worm-like chain (WLC) model predict a slightly smaller favorable loop length

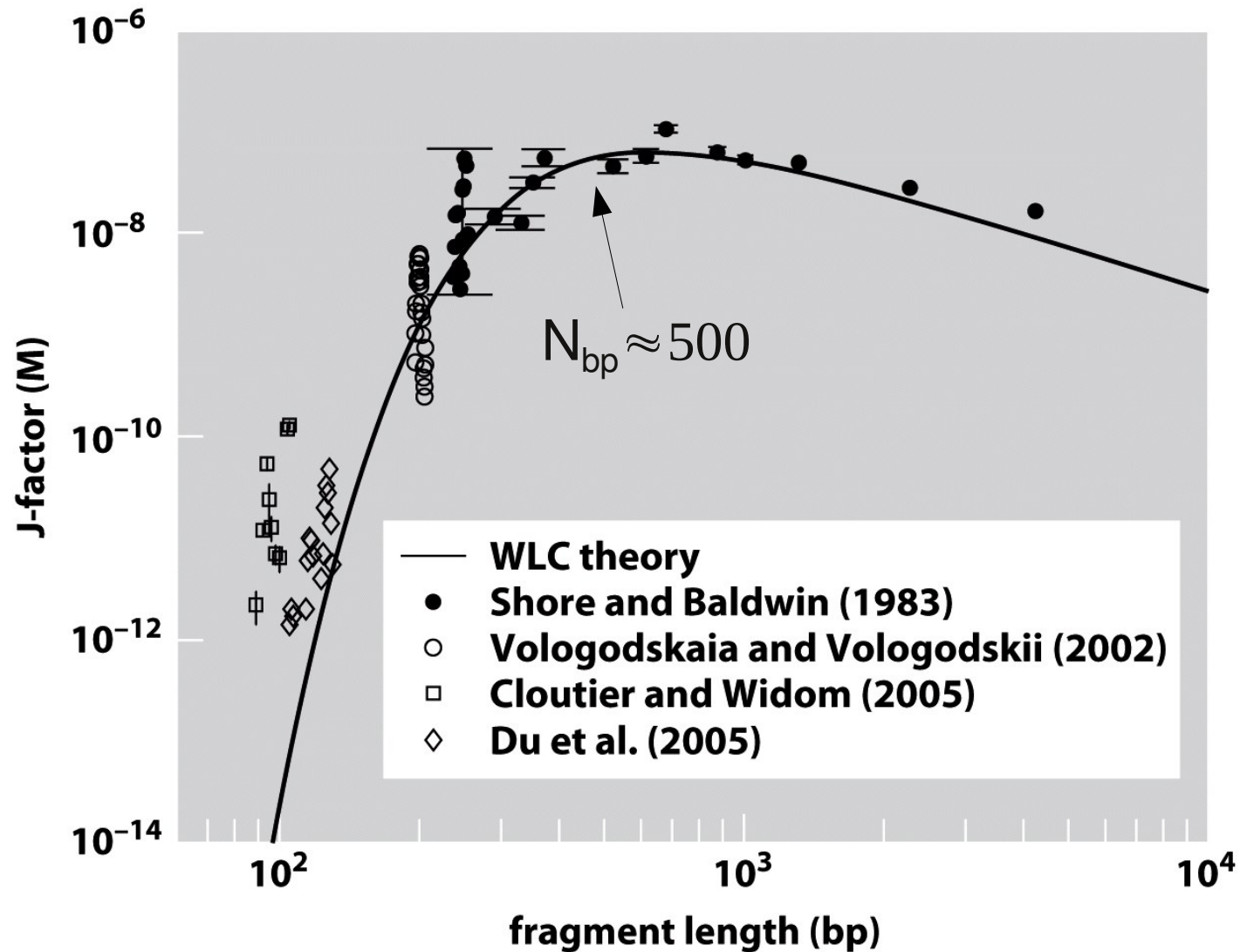


Figure 10.12 Physical Biology of the Cell (© Garland Science 2009)

What is the J-factor?

Cyclization experiments report a quantity J [in units of Concentration]:

$$J \propto e^{-\beta \Delta G_{\text{loop}}}$$

So that the minimum of the free energy of looping is equivalent to the maximum of J.

DNA Packing: From Viruses to Eukaryotes

$$\text{volume fraction } \nu = \frac{\Omega_{\text{genome}}}{\Omega_{\text{container}}} \approx \frac{N_{\text{bp}} \times 1 \text{ nm}^3}{\Omega_{\text{container}} [\text{nm}^3]}$$

L_{genome}	$5 \times 10^4 \text{ bp}$	$5 \times 10^6 \text{ bp}$	10^9 bp	10^9 bp
ν	0.6	0.1	0.02	0.002

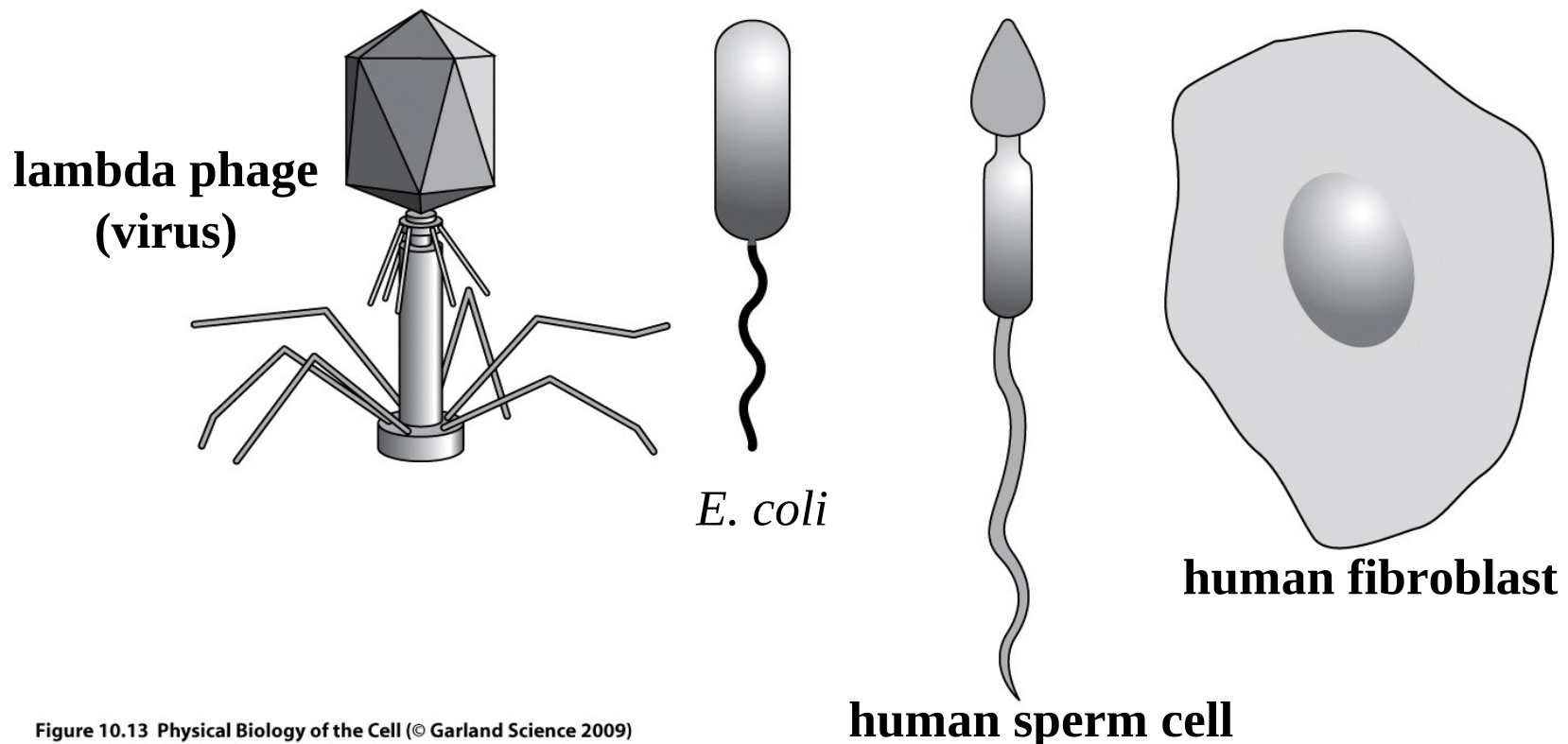


Figure 10.13 Physical Biology of the Cell (© Garland Science 2009)

The DNA Packing Compaction Ratio

- a) lambda phage with spherical capsid of radius of 27 nm holding 48,500 base pairs:

$$v = \frac{N_{bp} \text{ nm}^3}{\frac{4}{3} \pi R^3 \text{ nm}^3} \approx \frac{5 \times 10^4}{4 \times 27^3} \approx 0.6$$

- b) bacterial nucleoid: a sphere of radius 0.25 μm holding 5×10^6 base pairs:

$$v \approx \frac{5 \times 10^6}{4 \times 250^3} \approx 0.1$$

- c) human sperm cell with a spherical nucleus of radius of 2.5 μm holding 10^9 base pairs:

$$v \approx \frac{10^9}{4 \times 2500^3} \approx 0.02$$

- d) human fibroblast nucleus of radius of 5 μm holding 10^9 base pairs:

$$v \approx \frac{10^9}{4 \times 5000^3} \approx 0.002$$

The Problem of Viral DNA Packing (check “viper.com” for a databank of viral structures)

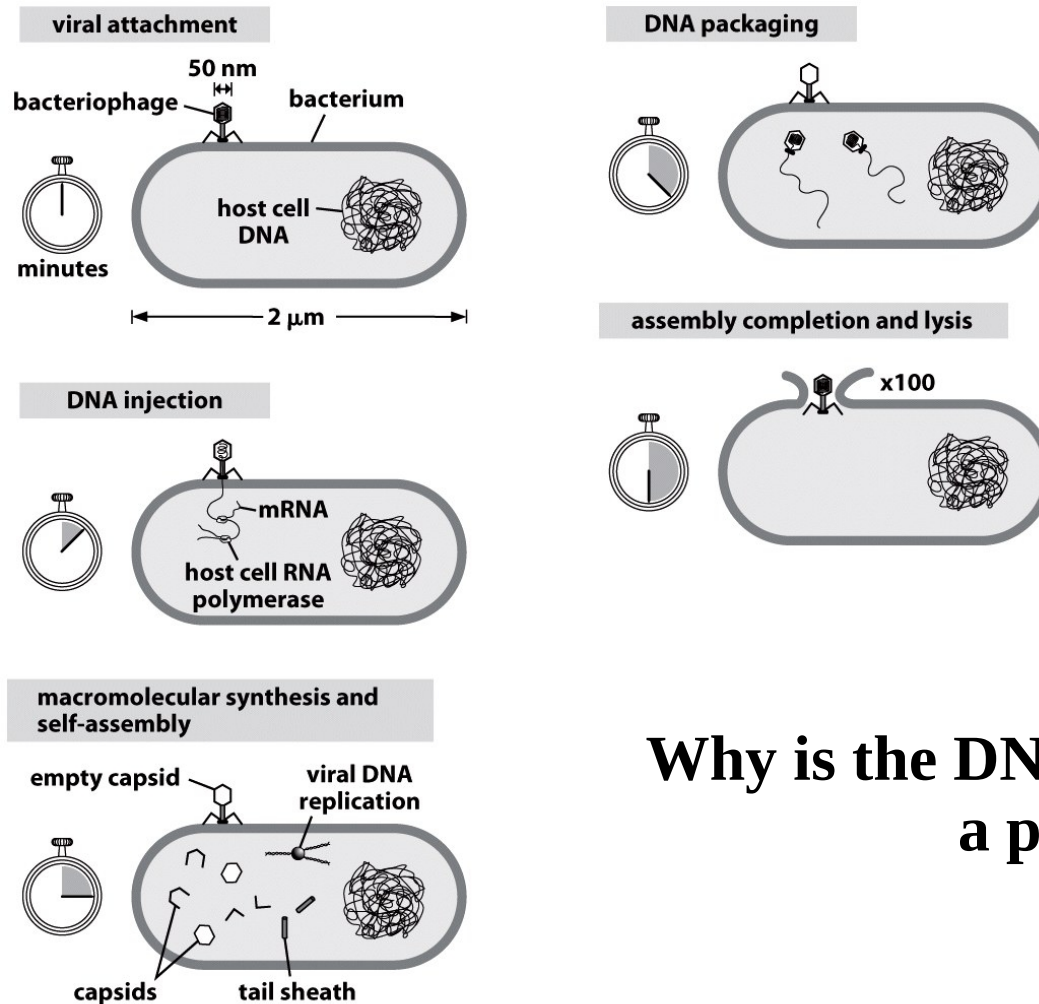
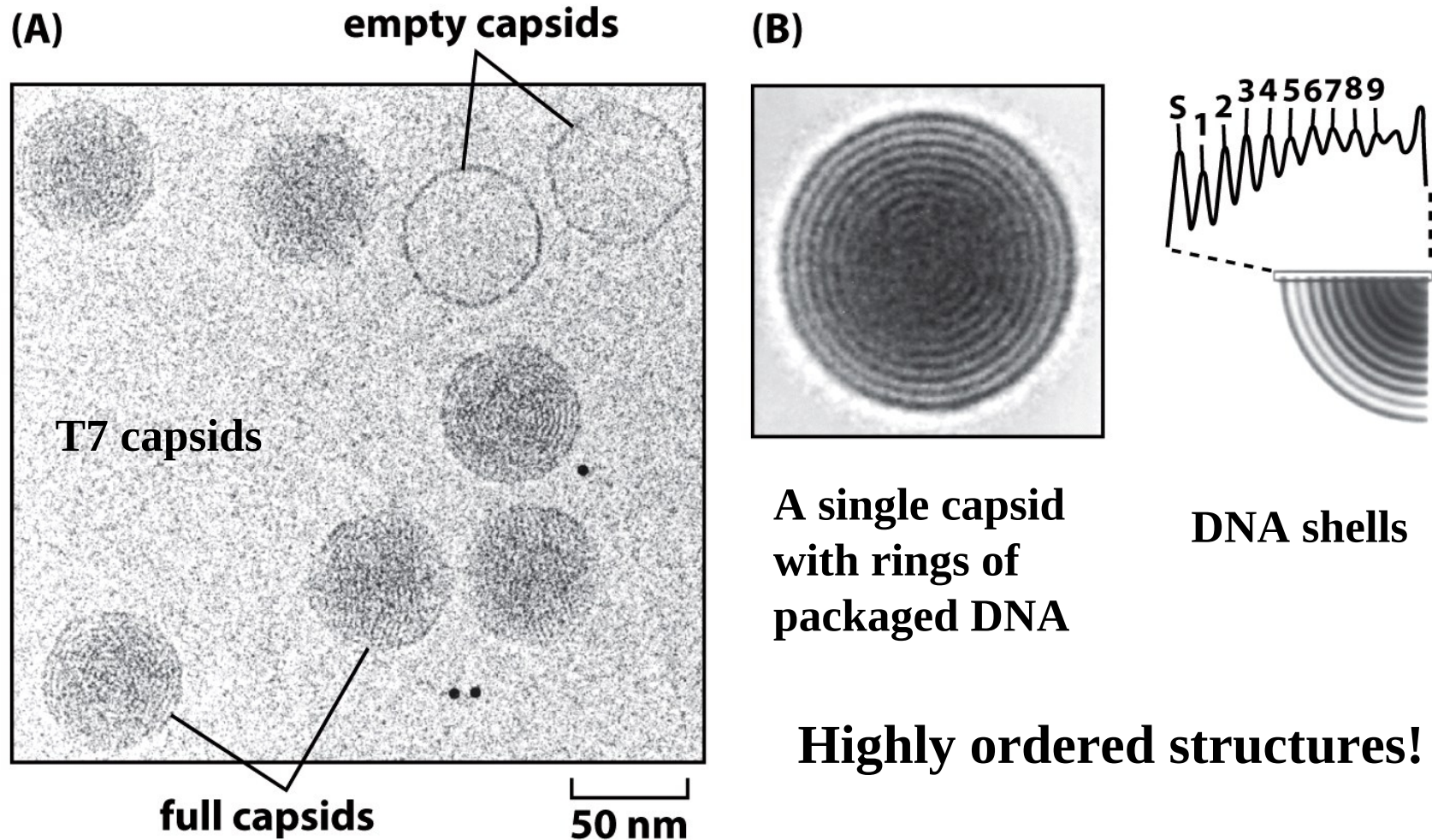


Figure 3.20 Physical Biology of the Cell (© Garland Science 2009)

Why is the DNA packing in viruses a problem?

Cryo-electron microscopy images of packaged DNA



$$\text{capsid volume : } V_{\text{capsid}} \approx L_{\text{DNA}} d_S^2 \rightarrow d_S \propto \frac{1}{L_{\text{DNA}}^{1/2}}$$

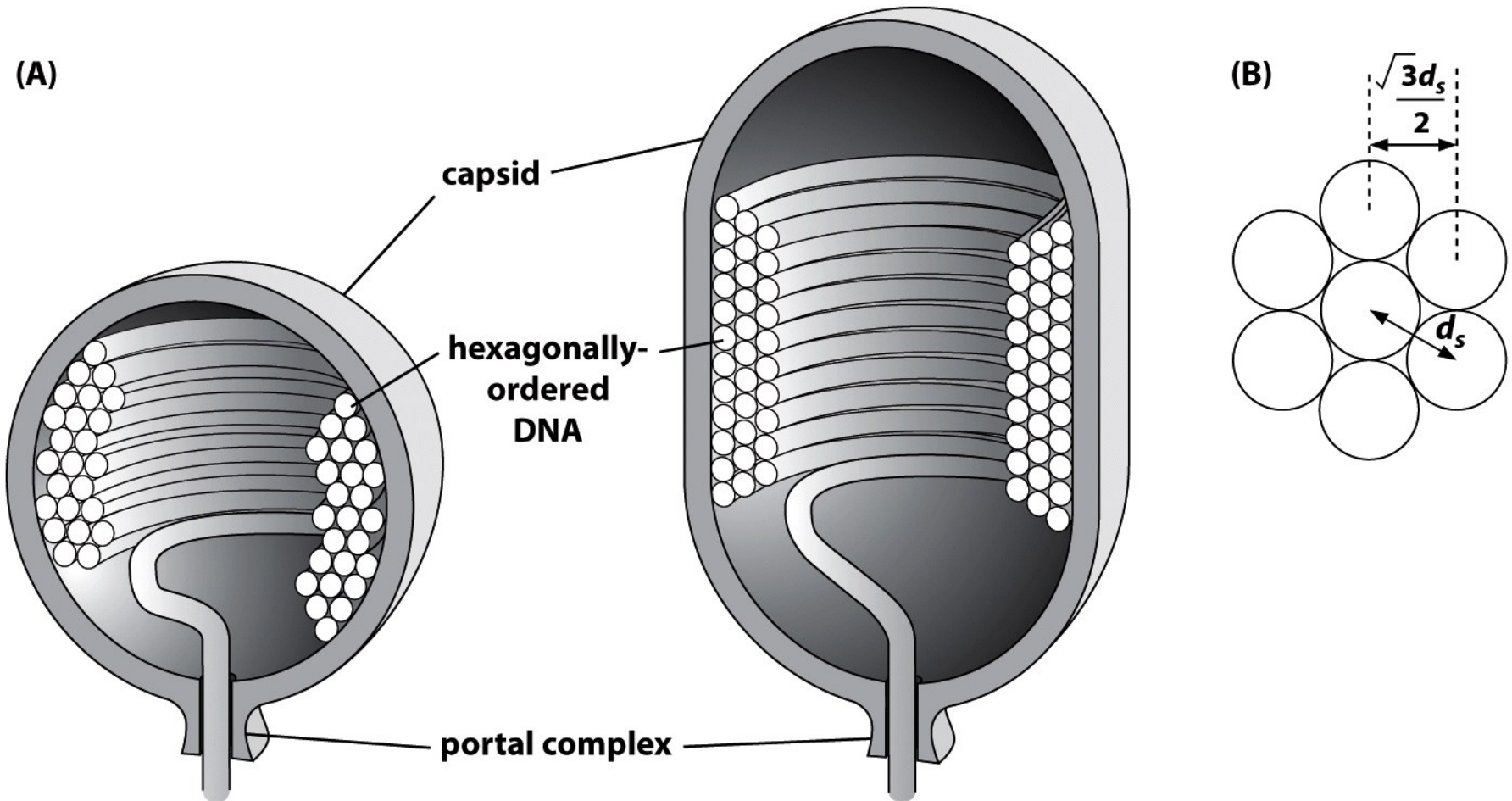


Figure 10.15 Physical Biology of the Cell (© Garland Science 2009)

Approximately correct scaling, though not on a large range

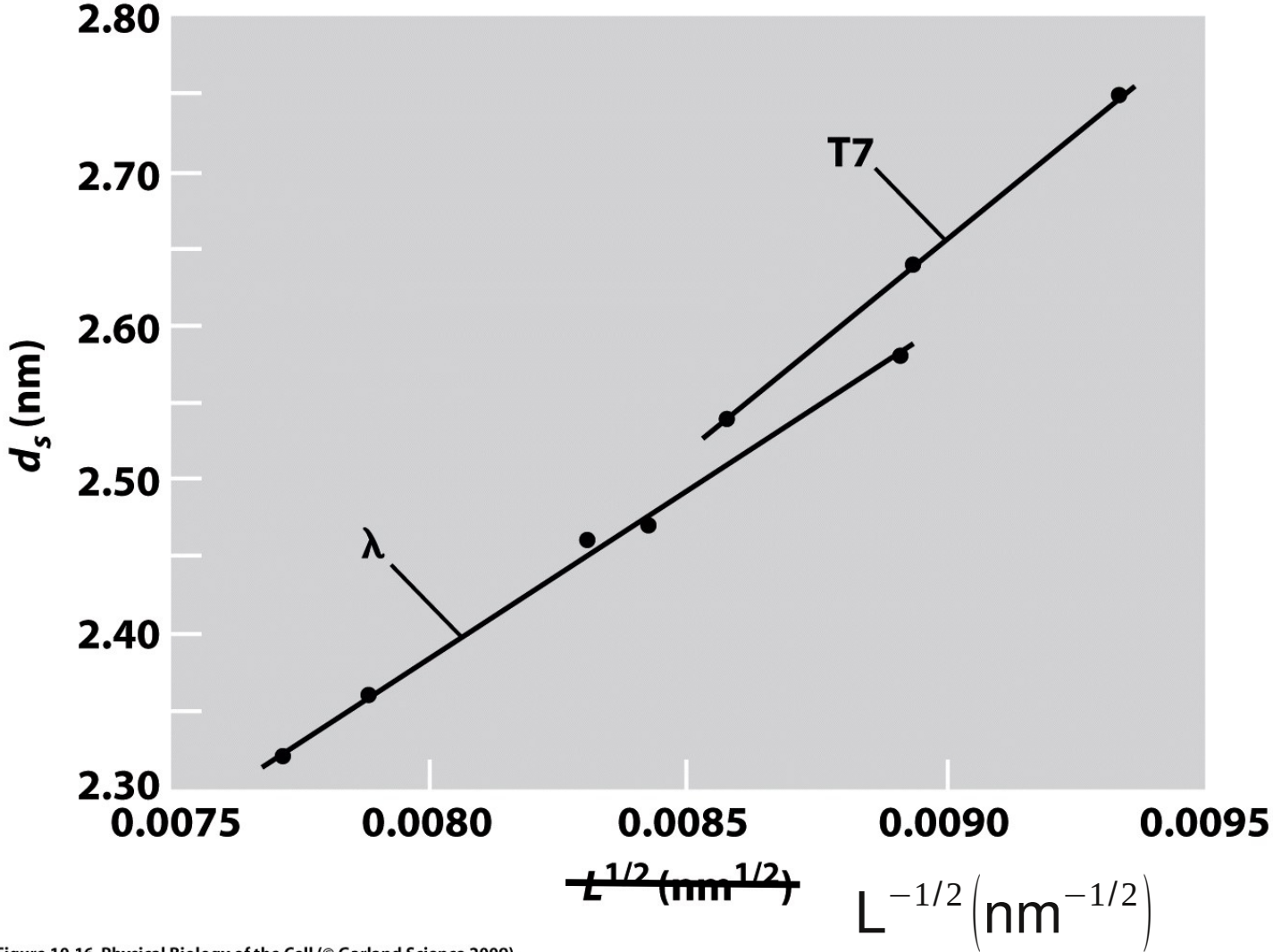


Figure 10.16 Physical Biology of the Cell (© Garland Science 2009)

Why does the DNA packing in viruses require energy?

- the entropic spring effect (DNA tends to spread out)
- elastic bending on the scale smaller than the persistence length of 50 nm
- strongly negatively charged DNA (tends to avoid itself)
- the entropic contribution is about 10-times smaller than the bending and electrostatic free energy associated with DNA packing (in viruses):

$$G_{\text{tot}}(d_s, L) \approx G_{\text{bend}}(d_s, L) + G_{\text{charge}}(d_s, L)$$

- the force that resists the packing is then:

$$F = \frac{-dG_{\text{tot}}(d_s, L)}{dL}$$

How can we measure the force needed to pack the DNA?

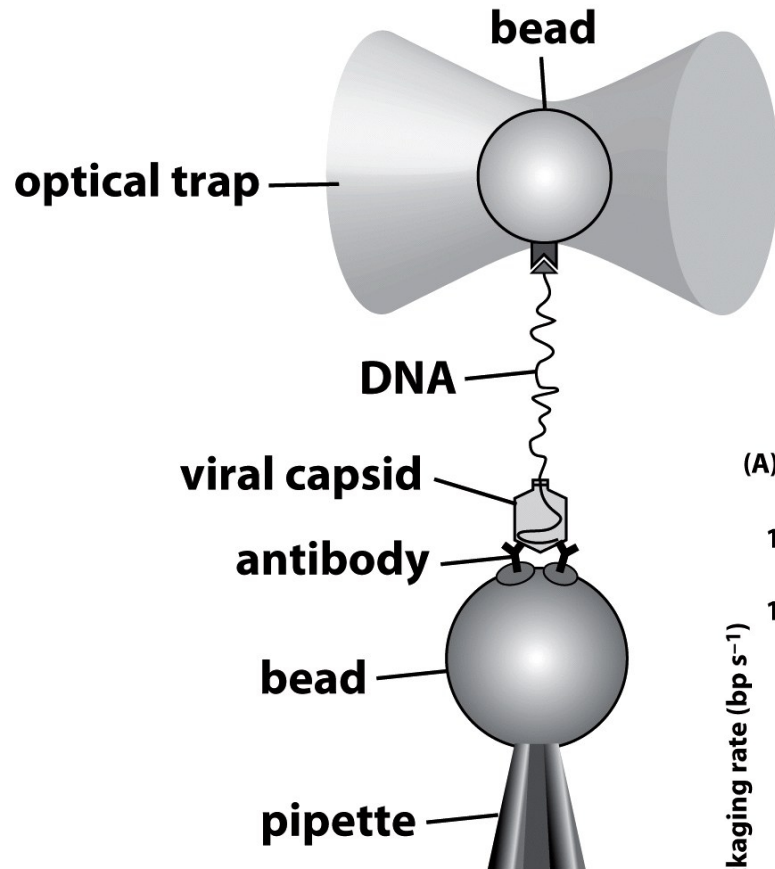


Figure 10.17 Physical Biology of the Cell (© Garland Science 2009)

Optical tweezers: pulling DNA against the ATP-consuming motor

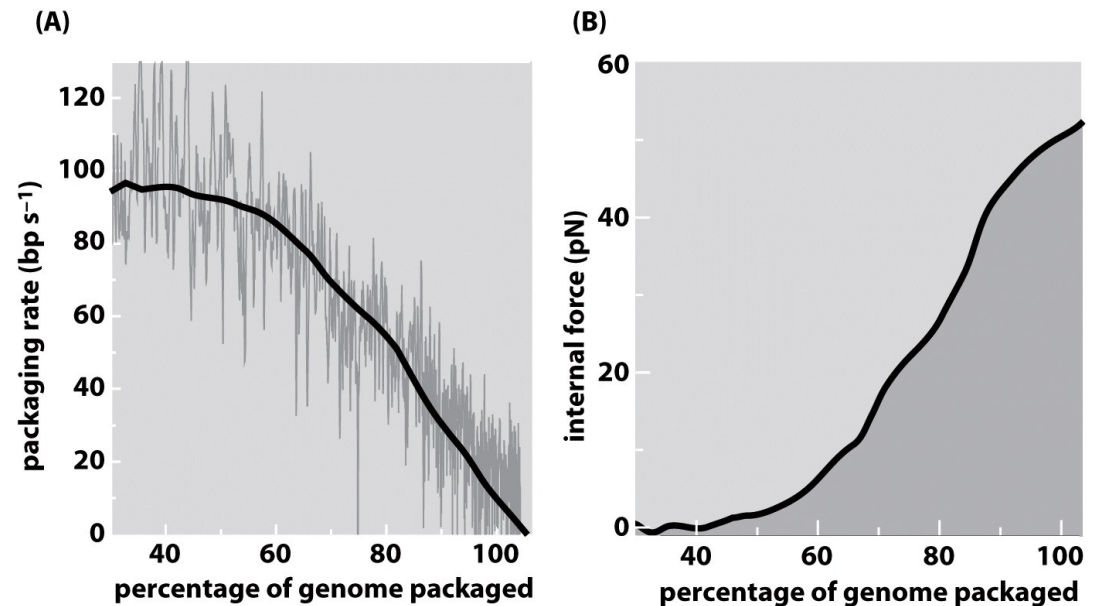


Figure 10.18 Physical Biology of the Cell (© Garland Science 2009)

Elastic Bending Contribution to the Free Energy: Circular Hoops

$$E_{\text{loop}} = \frac{\pi EI}{R} = \frac{\pi \xi_P k_B T}{R} \rightarrow G_{\text{bend}} = \pi \xi_P k_B T \sum_i \frac{N(R_i)}{R_i}$$

$$\sum_i \rightarrow \frac{2}{\sqrt{3} d_s} \int dR' \quad \frac{\sqrt{3}}{2} d_s \dots \text{distance between DNA strands}$$

$$G_{\text{bend}} = \frac{2 \pi \xi_P k_B T}{\sqrt{3} d_s} \int_R^{R_{\text{out}}} \frac{N(R')}{R'} dR'$$

$$\text{DNA length: } L = \frac{2}{\sqrt{3} d_s} \int_R^{R_{\text{out}}} 2 \pi R' N(R') dR'$$

cylindrical capsid of height z , radius R_{out} :

$$G_{\text{bend}}(R) = \frac{2 \pi \xi_P k_B T z}{\sqrt{3} d_s^2} \ln \left(\frac{R_{\text{out}}}{R} \right) \quad L(R) = \frac{2 \pi z}{\sqrt{3} d_s^2} (R_{\text{out}}^2 - R^2)$$

The second equation for L(R) can be used to express R:

$$R = R_{\text{out}} \sqrt{1 - \frac{\sqrt{3} d_s^2 L}{2 \pi z R_{\text{out}}^2}}$$

And the final expression for the free energy of bending:

$$G_{\text{bend}} = \frac{-\pi \xi_P k_B T z}{\sqrt{3} d_s^2} \ln \left(1 - \frac{\sqrt{3} d_s^2 L}{2 \pi z R_{\text{out}}^2} \right)$$

And the force associated with accumulated bending energy:

$$f(L) = \frac{-dG_{\text{bend}}}{dL} = \frac{-\frac{\xi_P k_B T}{2 R_{\text{out}}^2}}{1 - \frac{\sqrt{3} d_s^2 L}{2 \pi z R_{\text{out}}^2}}$$

Electrostatic Contribution to the Free Energy of DNA Packing In Viruses

- experiment that measures osmotic pressure versus DNA spacing d_s
- assume that parallel strands interact via a pair potential per unit length (only nearest neighbors): $v(d_s)$
- if we experimentally determine the pressure, we can compute the interaction energy and obtain the pair potential $v(d_s)$

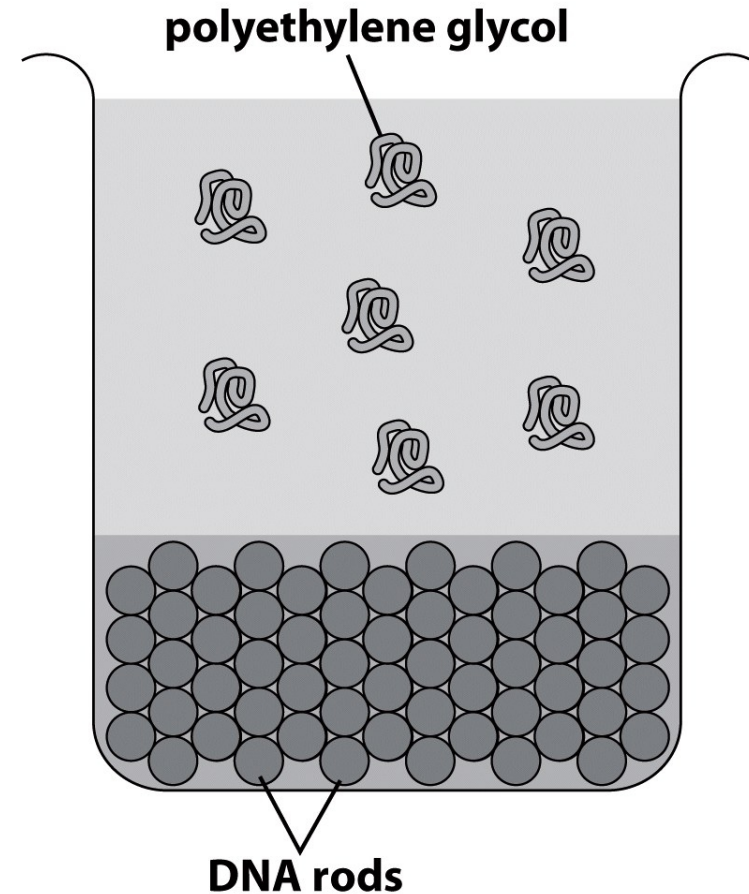


Figure 6.22 Physical Biology of the Cell (© Garland Science 2009)

Consider N parallel strands of length l , each packed into a hexagonal array with a spacing d_s : $G_{\text{charge}} = 3Nl v(d_s)$

(a factor of 3 = $1/2 \times 6$ for 6 nearest neighbors in the array)

The volume of the assembly is: $V = \frac{\sqrt{3}}{2} N d_s^2 l$

The pressure can be calculated as:

$$p(d_s) = \frac{-dG_{\text{charge}}}{dV}, \quad dV = Nl\sqrt{3} d_s dd_s$$

So that the force is:

$$f(d_s) = \frac{d v(d_s)}{d d_s} = \frac{1}{\sqrt{3}} p(d_s) d_s$$

Experimental observation was (Textbook, page 245):

$$p(d_s) = F_0 e^{-d_s/c}$$

Which leads us to the final expressions:

$$v(d_s) = \frac{1}{\sqrt{3}} F_0 (c^2 + c d_s) e^{-d_s/c}$$

$$G_{\text{charge}} = \sqrt{3} F_0 (c^2 + c d_s) L e^{-d_s/c}, \quad L = Nl \dots \text{total DNA length}$$

This electrostatic contribution can be experimentally controlled through ionic concentration, which affects the energy through F_0 whereas $c \approx 0.27 \text{ nm}$ is more or less constant over a wide range of salt conditions.

The total energy associated with DNA packing in viruses is:

$$G_{\text{tot}} = G_{\text{bend}} + G_{\text{charge}}$$

$$G_{\text{tot}} = \frac{-\pi \xi_P k_B T z}{\sqrt{3} d_s^2} \ln \left(1 - \frac{\sqrt{3} d_s^2 L}{2 \pi z R_{\text{out}}^2} \right) + \sqrt{3} F_0 (c^2 + c d_s) L e^{-d_s/c}$$

We need to find the optimal spacing by minimizing the total free energy (at fixed DNA length) with respect to the spacing:

$$\frac{\partial G_{\text{tot}}}{\partial d_s} = 0 \quad \rightarrow \quad d_s = d_s(L)$$

Then use this relationship in the expression for the force $F(L)$:

$$F(L) = \frac{-\partial G_{\text{tot}}}{\partial L}$$

Forces for bacteriophage viruses T4, T7, HK97, lambda, and Φ 29

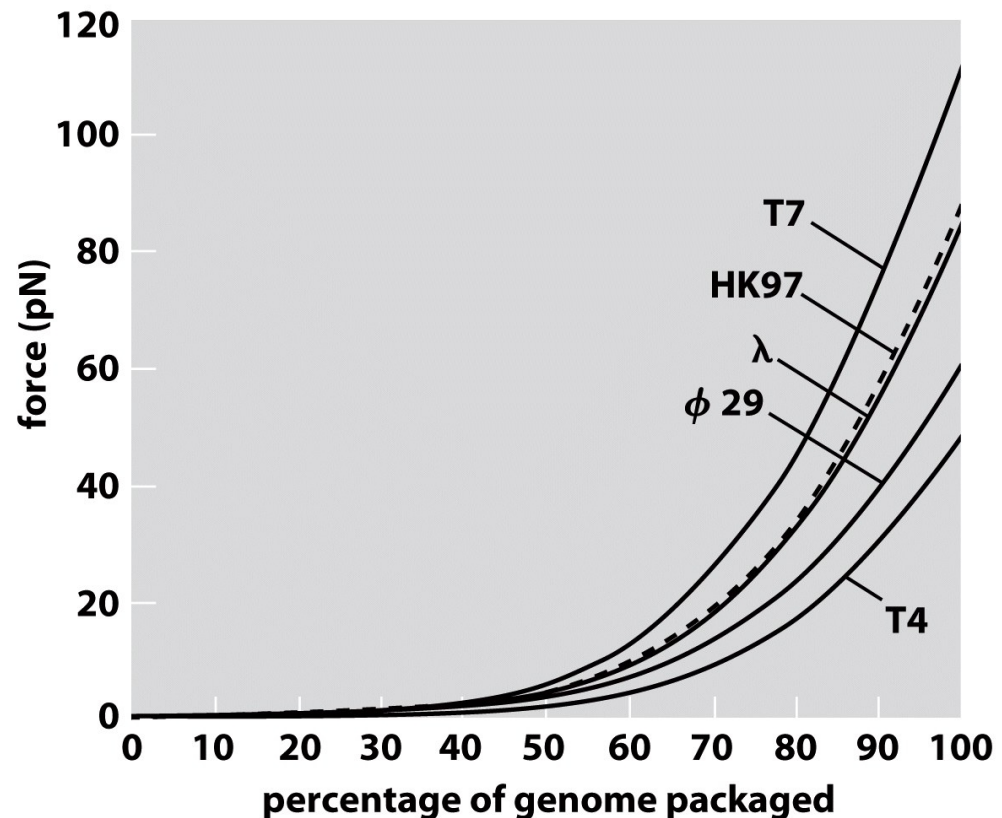


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